

ForeCAST :

Use of VHR satellite data for forest cartography

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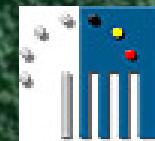
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I-MAGE
CONSULT



UCL- Dpt Sciences du Milieu et
de l'Aménagement du Territoire



Funded by BFP

Description of partnership

I-MAGE Consult

Private partner



Experienced in teledetection,
mapping of natural resources and
management of environmental
information



UCL- Dpt of
Environmental Sciences
and Land Use Planning

Scientific partner

Geomatics unit

Forestry unit



Objectives of the project

- ◆ To transfer results obtained in the field of scientific research to the private sector for forestry applications and regarding VHR satellite images processing techniques
- ◆ To make operational and validate those techniques and the know-how acquired in the research field
- ◆ To design a production workflow for the creation of forest maps meeting a number of needs of the forest managers and administrations



Objectives of the company

- ◆ Stay qualified with new technologies
 - VHR images
 - New segmentation and classification methods

- ◆ Expand and enhance his cartographic services related to forestry
 - New cartographic products
 - New clients and contacts



Satellite choice and test sites

- ◆ Choice of images : SPOT 5 and IKONOS-2
 - IKONOS-2 → VHR images, 1:10.000 scale products
 - SPOT5 → cheaper alternative
- ◆ Choice of three test sites
 - In Belgium, France, Morocco
 - To develop a robust protocol that can be applied in various conditions



Cartographic products identified

- ◆ Based on interviews of end-users
- ◆ Needs and requirement of end-users (scale from 1:10.000 to 1:20.000)
 - Poster (non orthorectified image)
 - Spatiomap (orthorectified image) } Licensing restrictions
 - Stands limits (delineation of forest stands and clearcuts)
 - Stands map (description of existing parcels)
 - Forest reference-map (when no information is available)





Method



From image to product

◆ Feasibility assessment

- Does the image provider allow it?
- Is it worth it ?
- Is it technically possible ?

◆ Methodological choices from raw images

- What is necessary ?
- What can be automated ?
- How to do it ?



Planimetric accuracy assessment

- ◆ Complementary to confusion matrix
- ◆ Concentrates on limits
- ◆ Hint on cartographic quality
 - Coherent with standard norm
 - Not scene dependent
- ◆ Correction of systematic errors



3 sources of planimetric errors

◆ Orthorectification

- Depends on quality of GCP and DEM
- Evaluated with RMS from check points

◆ Residual parallax

- Function of tree height
- Modelisation of accuracy and precision

◆ Confusion between classes

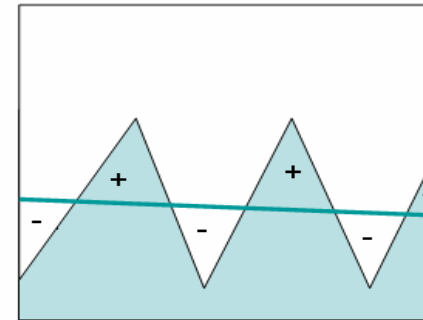
- Function of similarity between classes
- Estimation of accuracy and precision



Estimates of accuracy and precision

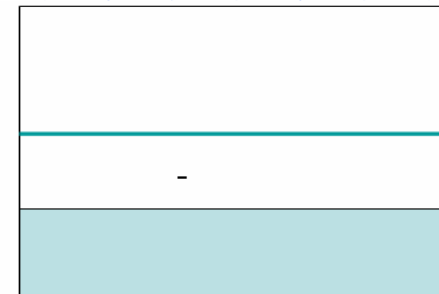
- ◆ Accuracy : absence of bias
 - Estimated by the normalised sum of signed area of conflict
- ◆ Precision : smallest range of errors
 - Estimated by the normalised sum of conflicting areas minus the bias

Good accuracy, bad precision



— : Reference

Bad accuracy, good precision



Object-oriented forest description

- ◆ Segmentation using e-Cognition
 - Multi-scale
 - Tuning between shape and color
- ◆ Different scale factor used for contextual analysis
- ◆ Enhanced object description
 - Radiometry
 - Texture
 - Shape



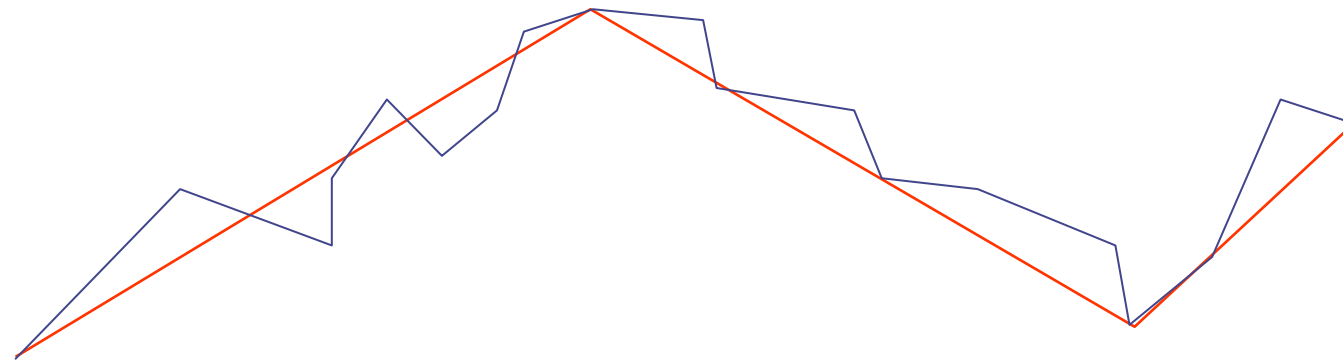
Image fusion skipped

- ◆ Object based approach
 - Segmentation uses all layers
 - ◆ Small structures from panchromatic
 - ◆ Large structures from multispectral
 - Values summarized per object
 - ◆ Texture from panchromatic
 - ◆ Spectral information from multispectral

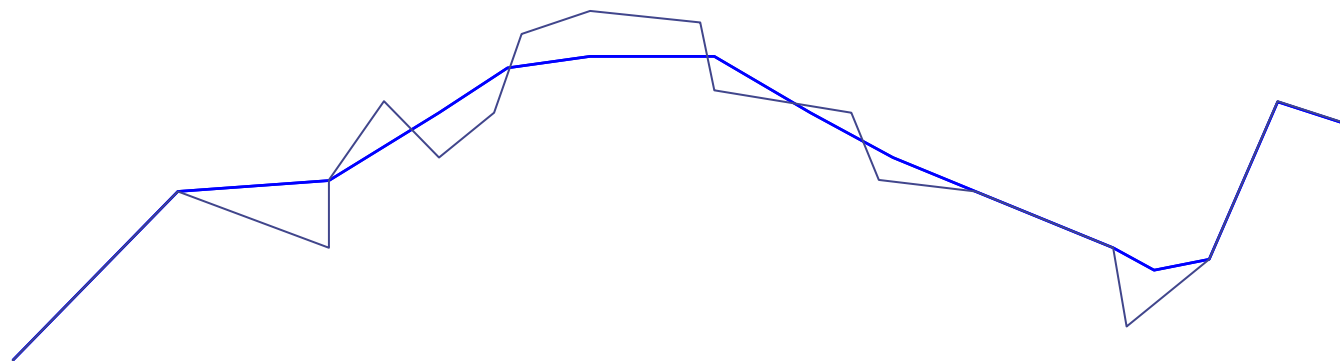


Simplification of the limits

- ◆ Comparison of 2 algorithms
 - Douglas-Poiker's point removal



- Middle line



Results and discussion



SRTM good enough for IKONOS

- ◆ Good results with RPC files
 - Needs less GCP's
- ◆ NGI DEM interpolated from contour lines
 - 0.8 m RMS Z
- ◆ Similar results for NGI and smoothed SRTM
 - NGI DEM : 1.24 RMS X and 1.37 RMS Y
 - Smoothed SRTM : 1.24 RMS X and 0.98 RMS Y
 - Non smoothed SRTM : 1.20 RMS X and 2.49 RMS Y
- ◆ Good GCP's difficult to obtain in forested areas



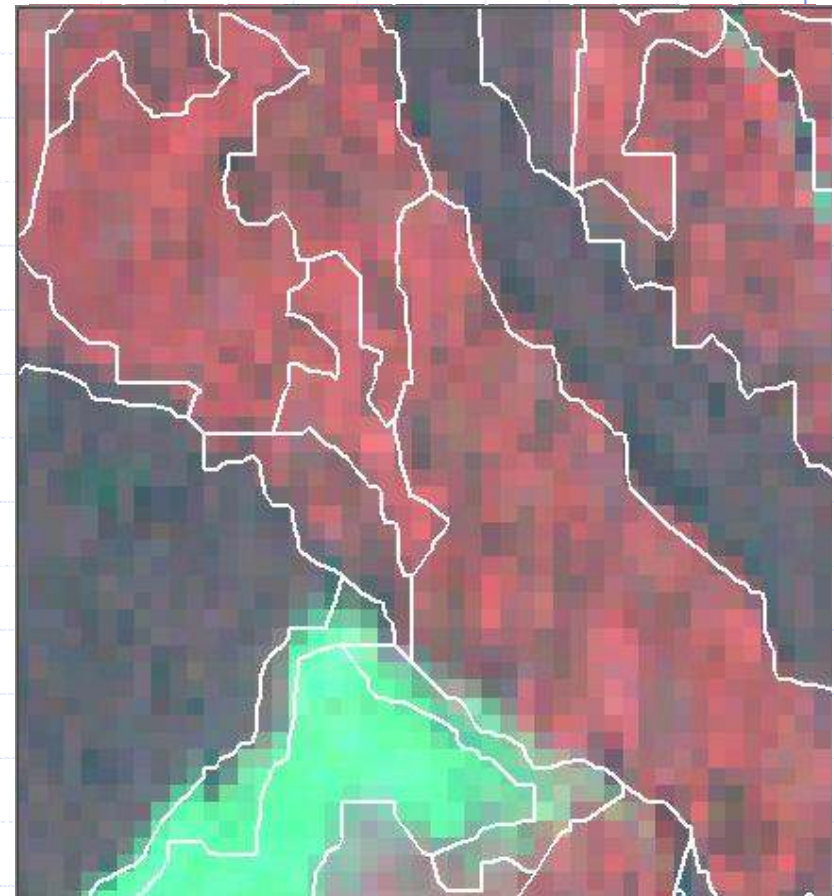
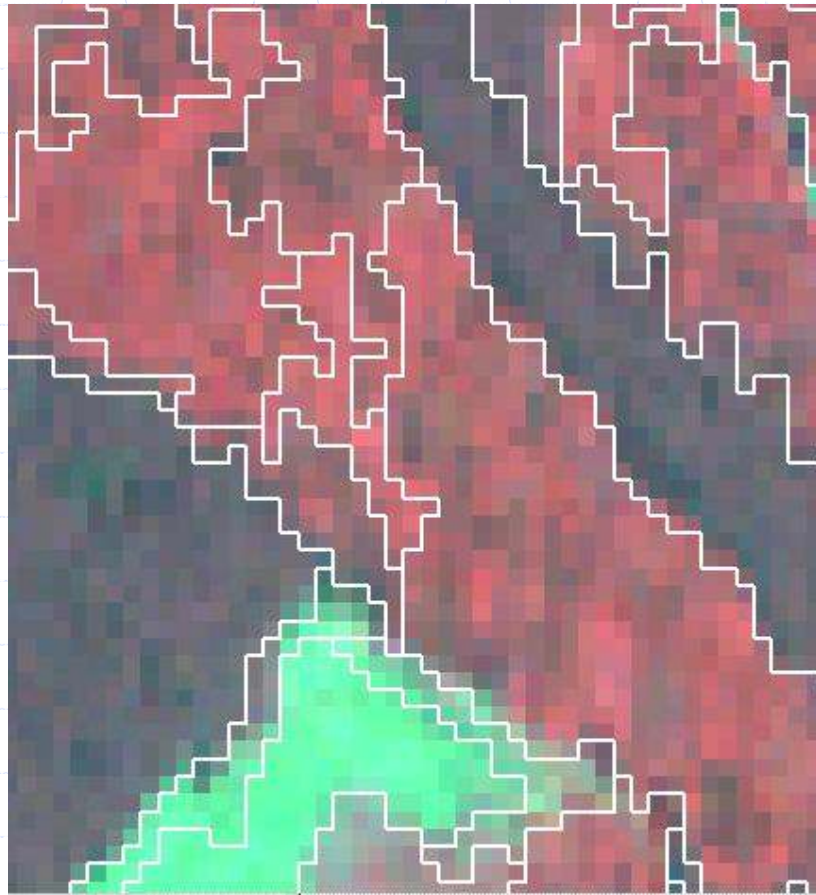
Forest stand maps

- ◆ Segmentation only is not sufficient
 - Small inclusions are also important
 - High scale factors not appropriate
 - Heterogenous area grouped as smaller regions
 - Large forest stands remain divided
- ◆ 2 solutions
 - Manual grouping
 - Classification-aided segmentation



Simplification improves visualisation

- ◆ Enhanced products for GIS or maps



Impact of simplification

- ◆ Limited effect on the bias
- ◆ Douglas-Poiker
 - Performs better on straight lines
 - Can create artifacts
- ◆ Middle-line algorithm
 - Reduction of the range of variation (up to 20 %)
 - Performs better on curved boundaries



IKONOS 1 m close to SPOT 5 m

- ◆ Summary of coniferous/residuous interfaces
- ◆ IKONOS panchromatic, 1M
 - Parallax errors std: 7.8 m
 - Segmentation errors std : 3.6 m
- ◆ IKONOS multispectral, 4M
 - Parallax errors std : 7.8 m
 - Segmentation errors std : 4.9 m
- ◆ SPOT 5 panchromatic, 5M
 - Parallax errors std : 6.5 m
 - Segmentation errors std : 6.8



Conclusions



Technological transfer in 3 steps

- ◆ Product description
 - What do end users really need ?
- ◆ Methodological development
 - What can we do ?
 - Is it worth doing it ?
- ◆ Knowledge transfer
 - How to and why doing it ?



Providing 1/20000 forest maps

- ◆ Orthorectification using SRTM
- ◆ No image fusion necessary
- ◆ Grouping of segments needed
 - Manual or classification based
- ◆ Close edge precision for SPOT 5 and IKONOS...
 - Parallax is main cause of errors
 - Confusions due to shade
- ◆ ...but
 - Smaller MMU with IKONOS
 - Better description with IKONOS



More to come...

◆ Classifications to be validated

- 15 classes in forests
- Distinctions between groups of species
- Age (height) classes
- Stand homogeneity (closed or open cover)

◆ Correction of parallax

- Using height from ancillary data or from image
- Using stereo pair



Thank you for your attention

