



# ASSIMIV (Part 1)

Artefact detection  
using image to map  
comparison

Namur,

12 February 2008

J. Radoux

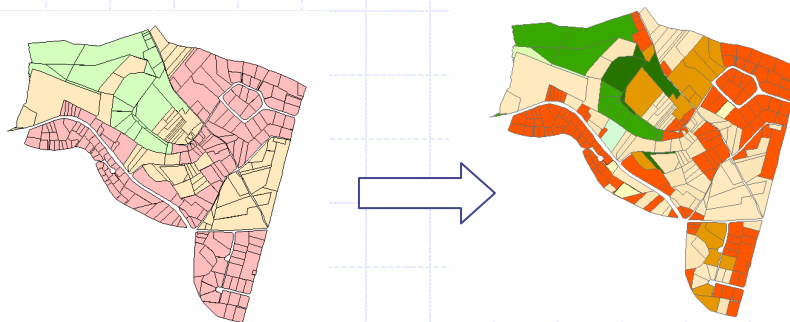
P. Defourny

# ASSIMIlation of Image in Vector

◆ Update



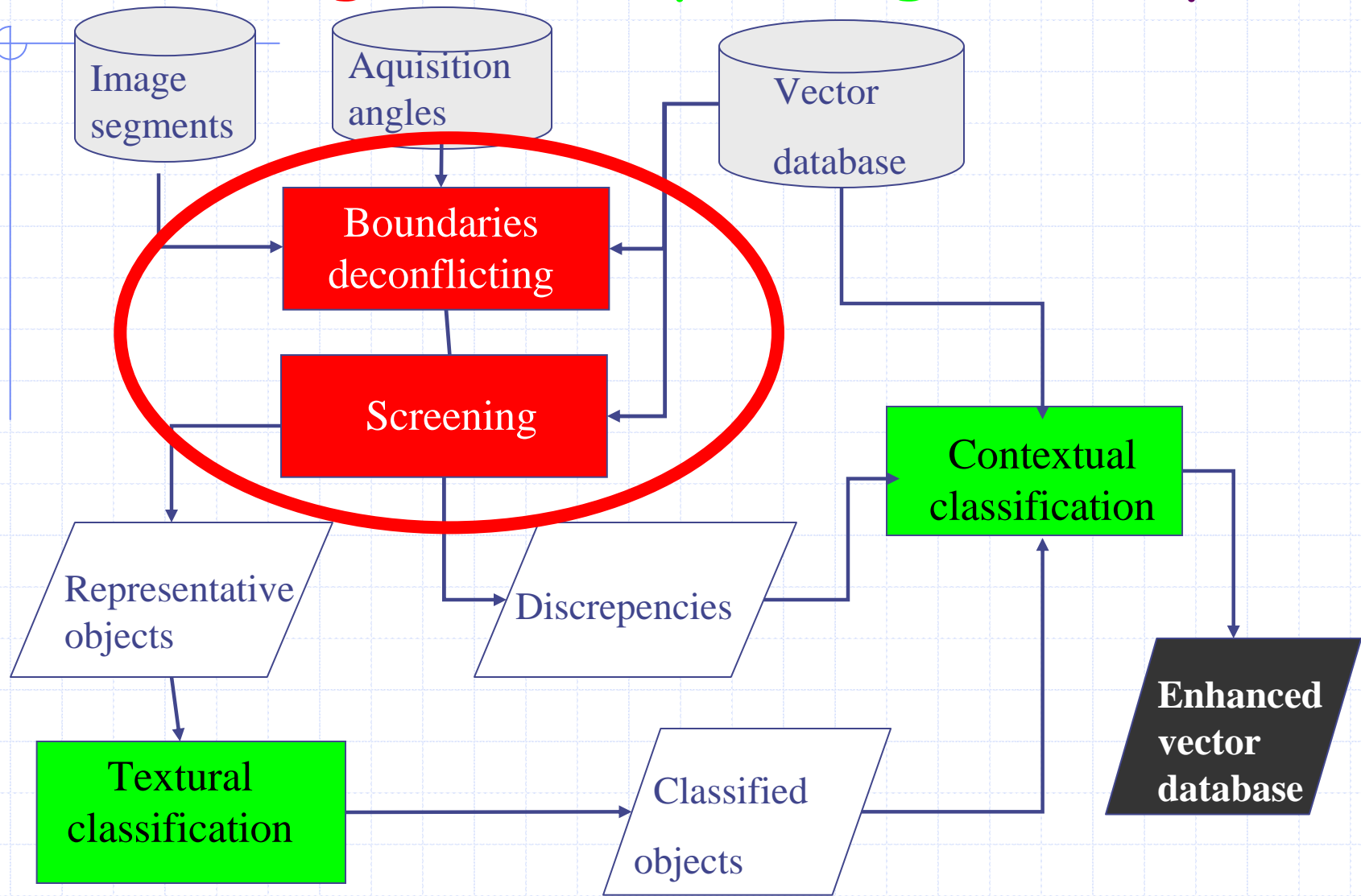
◆ Upgrade



For assimilation of VHR images into  
planimetrically accurate vector DB



# Screening then exploiting discrepancies



# 3 types of discrepancies...

## ◆ Update & upgrade

- Objects

## ◆ Artefacts

- Objects

## ◆ Planimetric errors

- Edges





# First step : boundary artefacts



# Consistent vector boundaries ?

- ◆ Adjust GIS database to pseudo ortho-image
  - Trigonometric model
- ◆ Transfer GIS labels to image-objects
  - Zonal majority filter
- ◆ Measure planimetric errors along edges
  - Accuracy and precision
- ◆ Detect potential artefacts
  - Statistical approach



# Trigonometric model

## ◆ Residual x-parallax shift

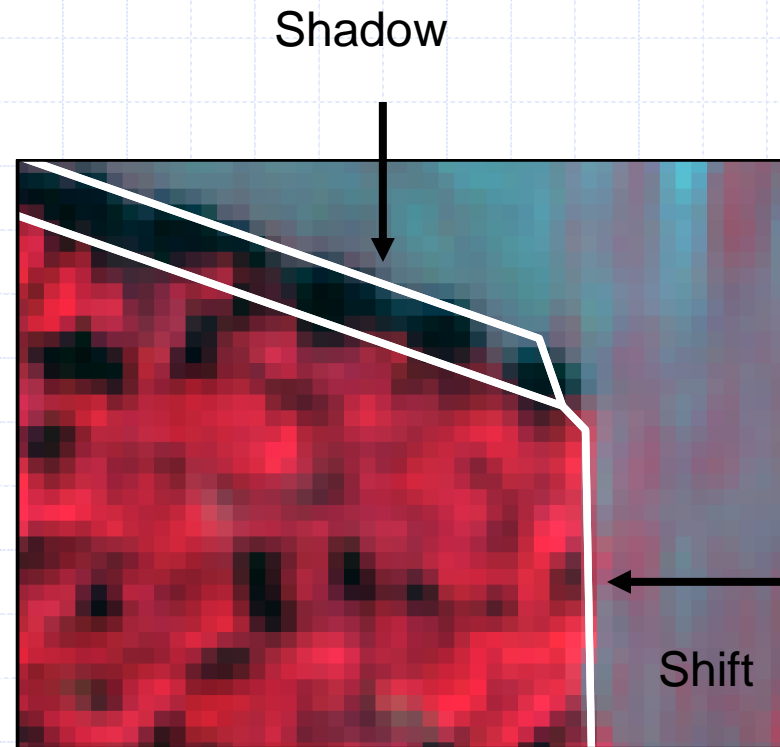
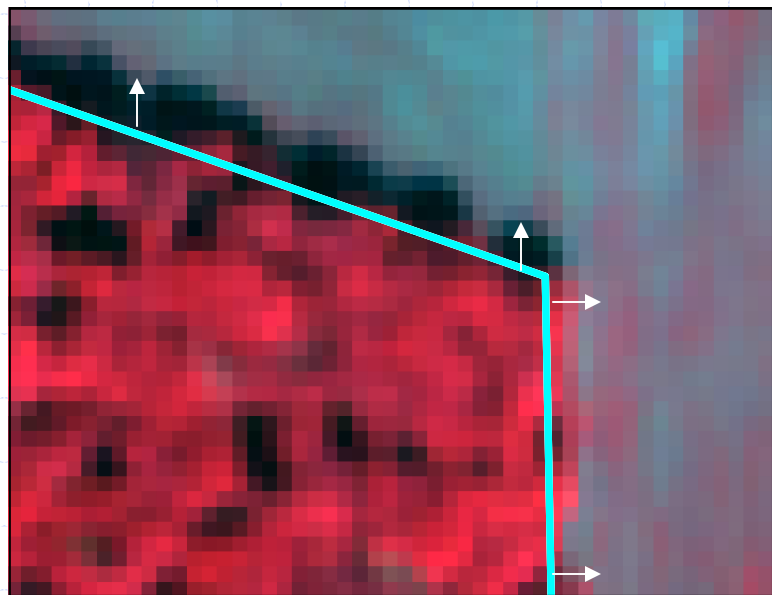
- Proportional to object height
- Function of the viewing zenith angle
- In the direction of the viewing azimuth angle
- $\text{Shift} = H * \tan(\text{VZA})$

## ◆ Apparent shift

- Vertical sides can be similar to the object top
  - ◆ E.g. hedges, but rarely buildings
- Vertical sides are part of the same object
  - No apparent shift when facing the satellite

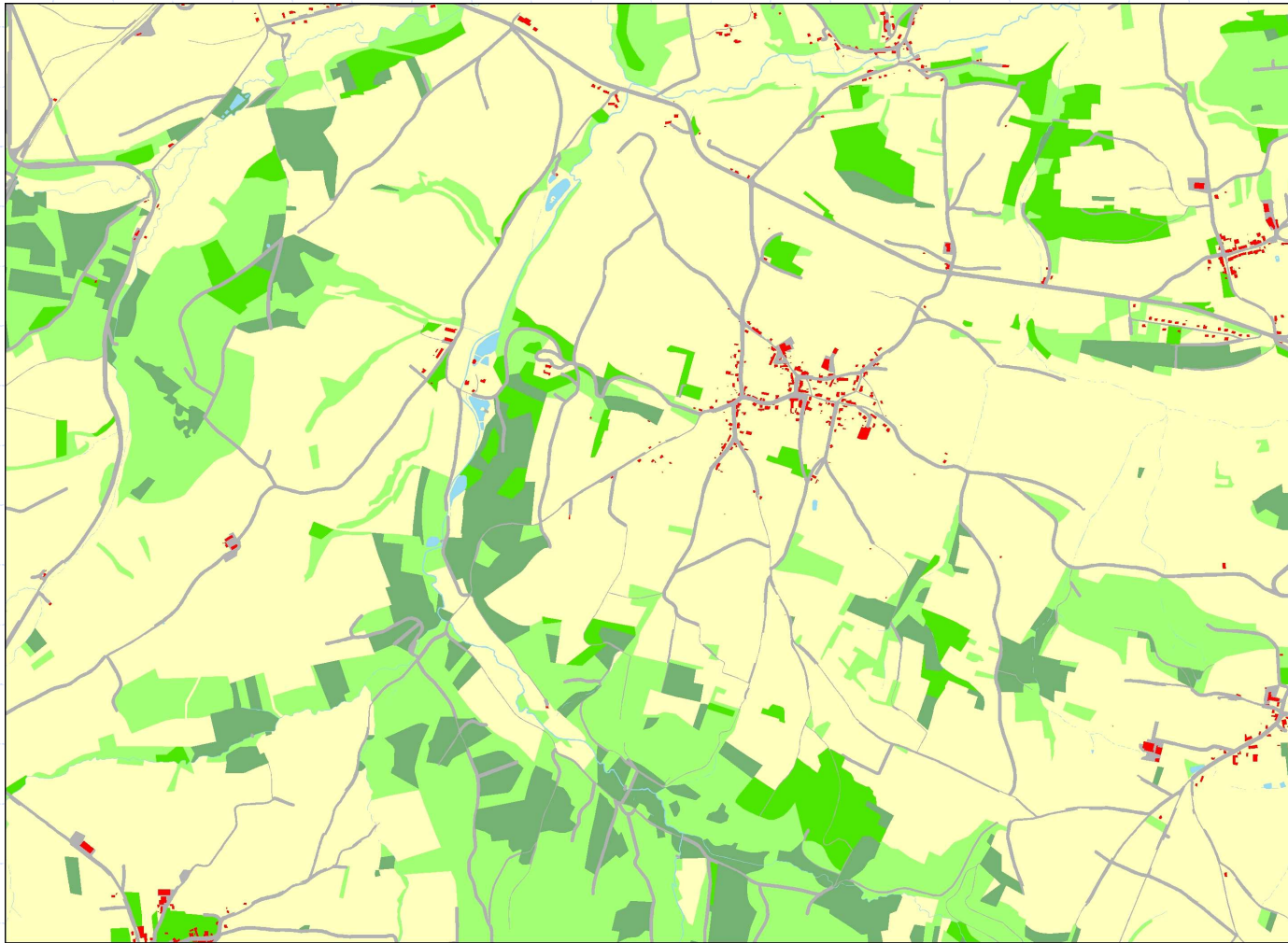


# Automated edge adjustment and shadow candidate detection





# Original vector database

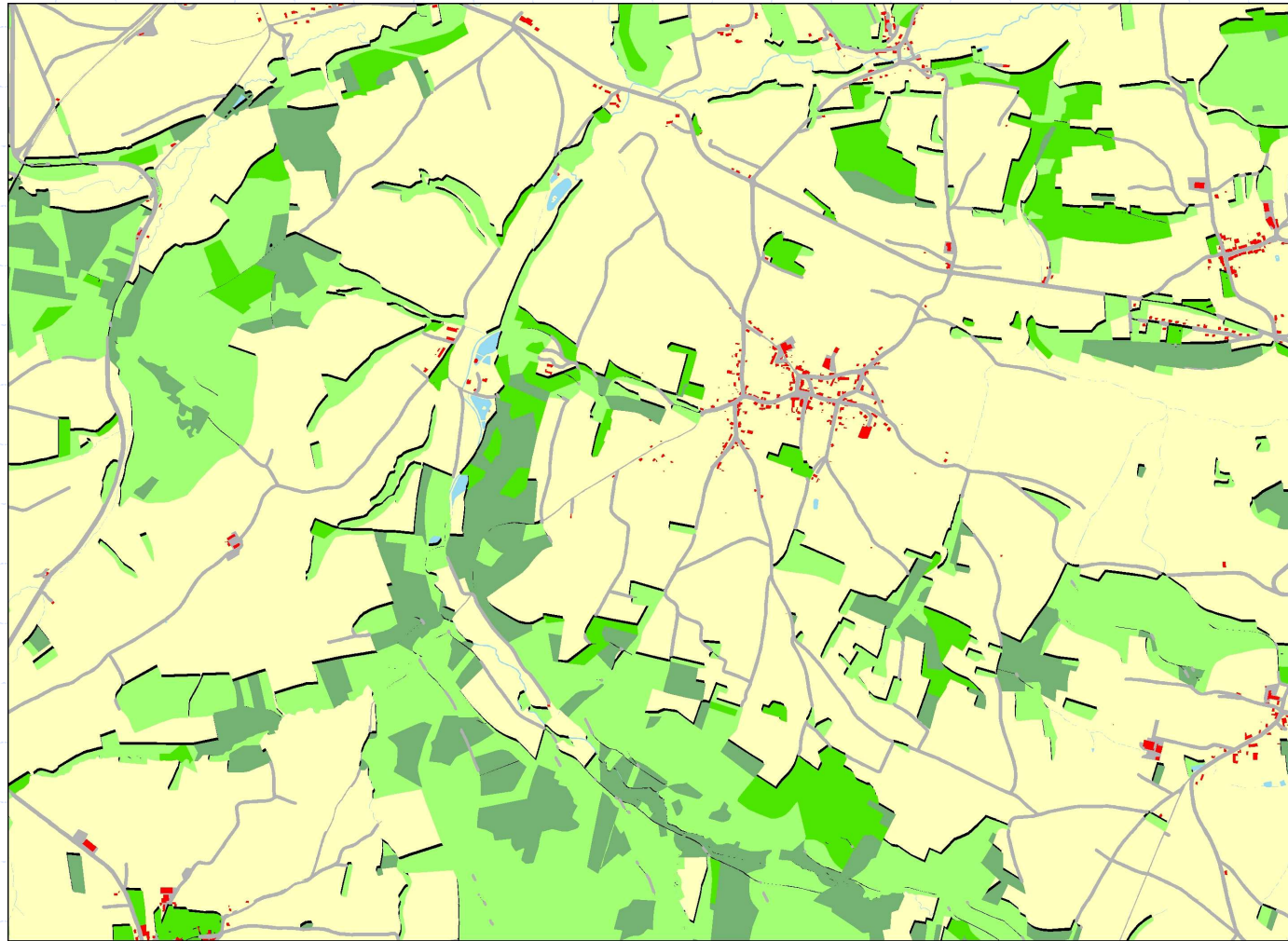


0 0.5 1 2 Km

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# Shade and parallax added



0 0.5 1 2 Km  
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# Quickbird image → over-segmentation

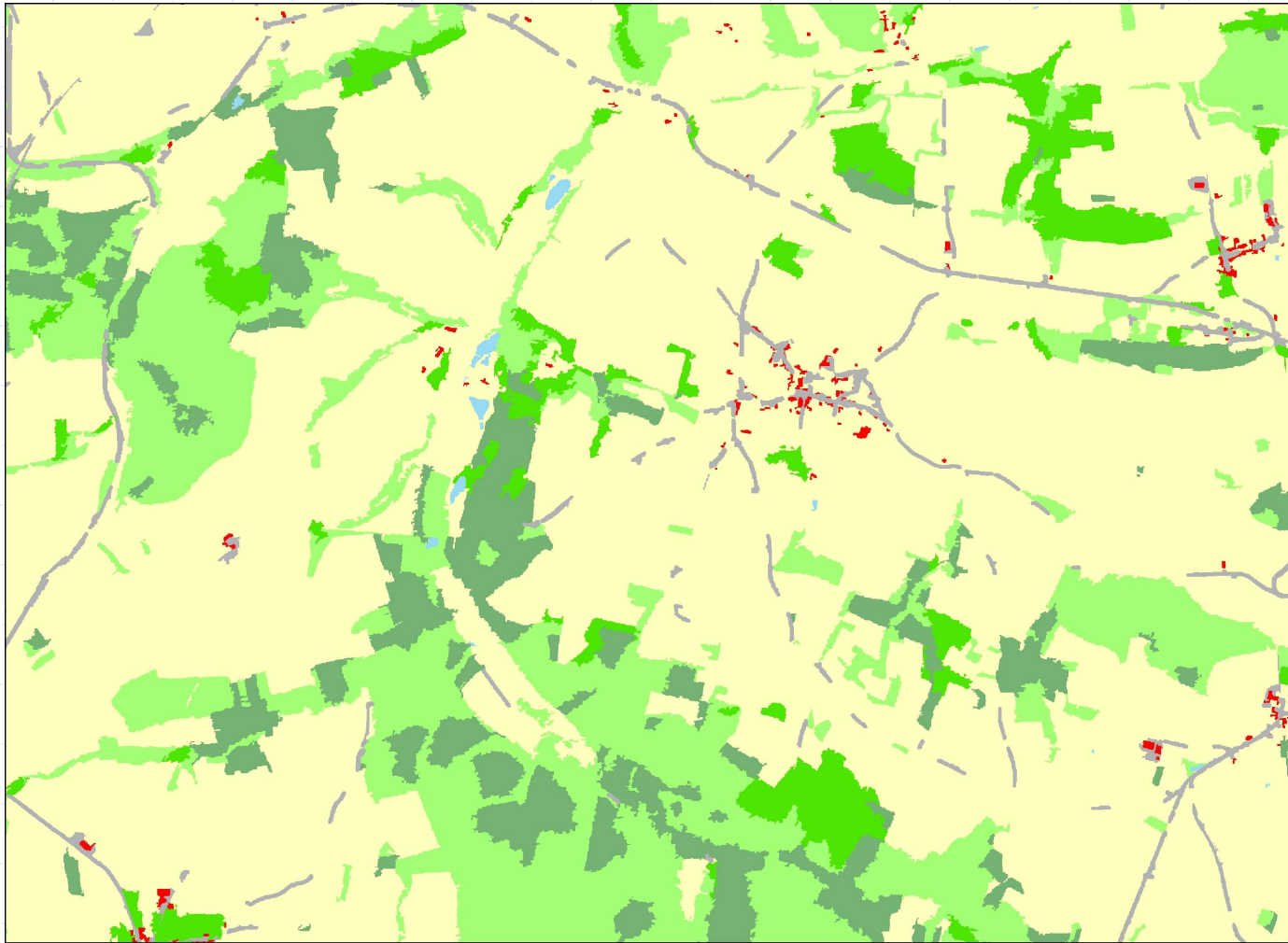


0 0.5 1 2 Km

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# Automated majority-based labelling



0 0.5 1 2 Km

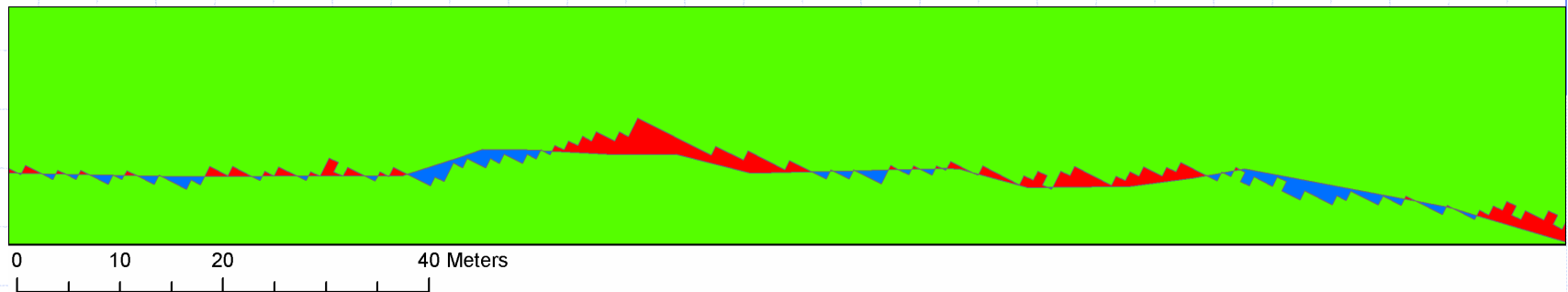


# Edge quality assessment

- ◆ Indicators for accuracy and precision
  - Edge based bias and standard deviation
- ◆ Parallax error
  - Rough height estimate (checked with shadows)
- ◆ Mislabeled polygons
  - Processed in object conflict detection (part 2)
- ◆ Other conflicts
  - Error above RMS and class uncertainty : update needed (GIS-based bias removal)
  - Errors below RMS or class uncertainty : tolerated



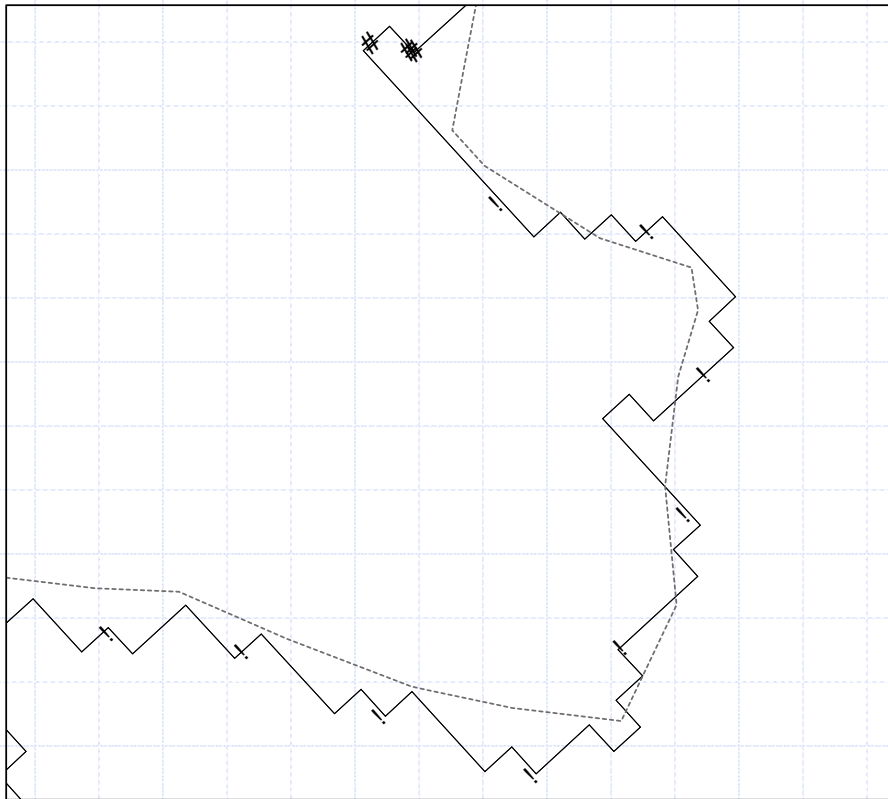
# Normalised bias : systematic errors



- ◆ Difference between **invasion** and **recession**
- ◆ Normalised by reference interface length
- ◆ Affected by
  - Edge definition (Database bias)
  - Image acquisition (Image bias)



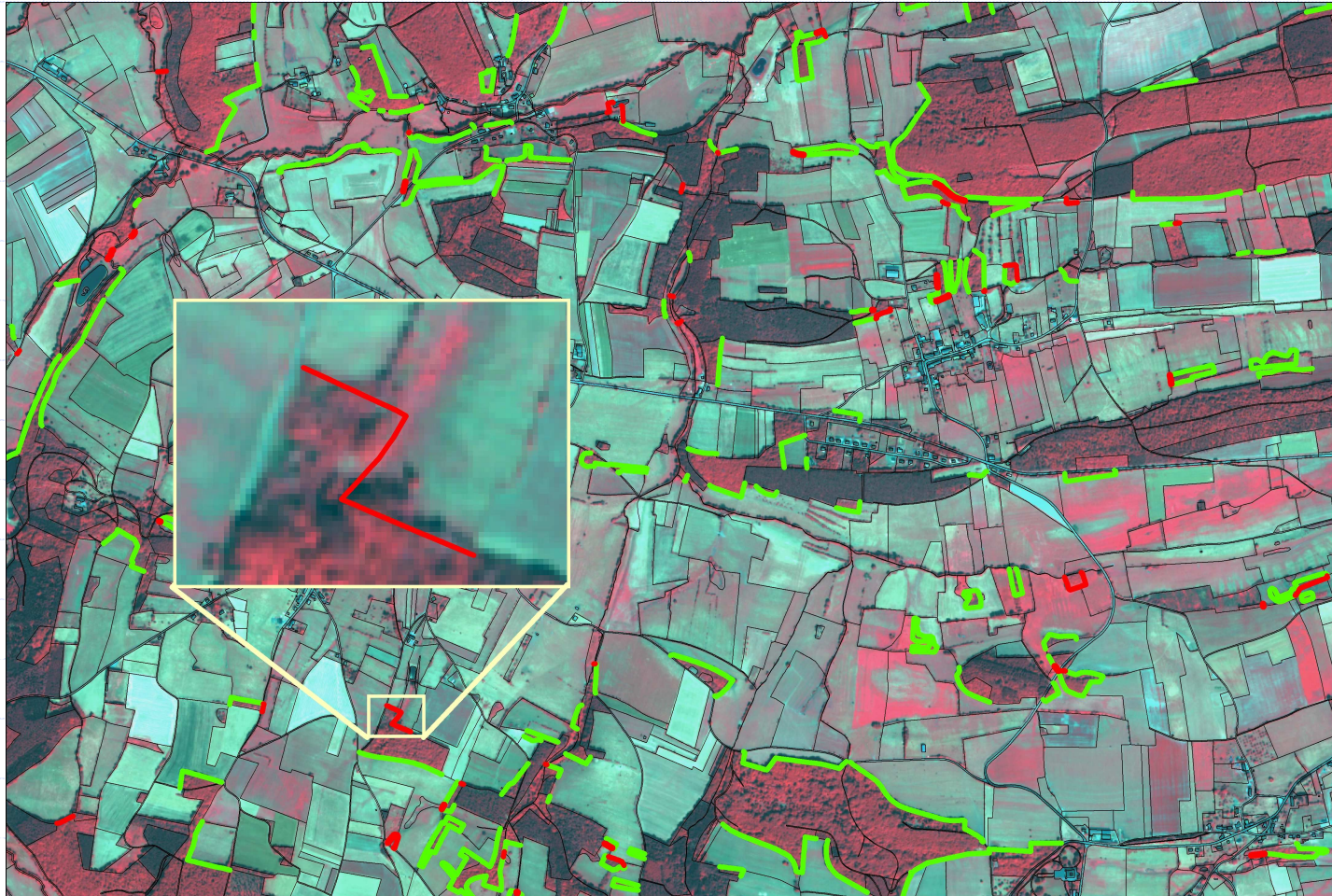
# Sampling for STD estimation



- ◆ Some edges are more reliable than others
  - Ecotones
  - Fuzzy edges
  - Simplified objects



E.g. : forest/crop fields boundaries







# Second part : Object conflicts



# Are « brother » sub-object similar ?

- ◆ Per field and per class assessment
  - Depends on the intra field heterogeneity
- ◆ Characteristic selection
  - Still to do...
  - Only spectral values used at this point
- ◆ Bi-modal iterative trimming
  - Use EM algorithm for bi-modal parameters
  - Likelihood treshold

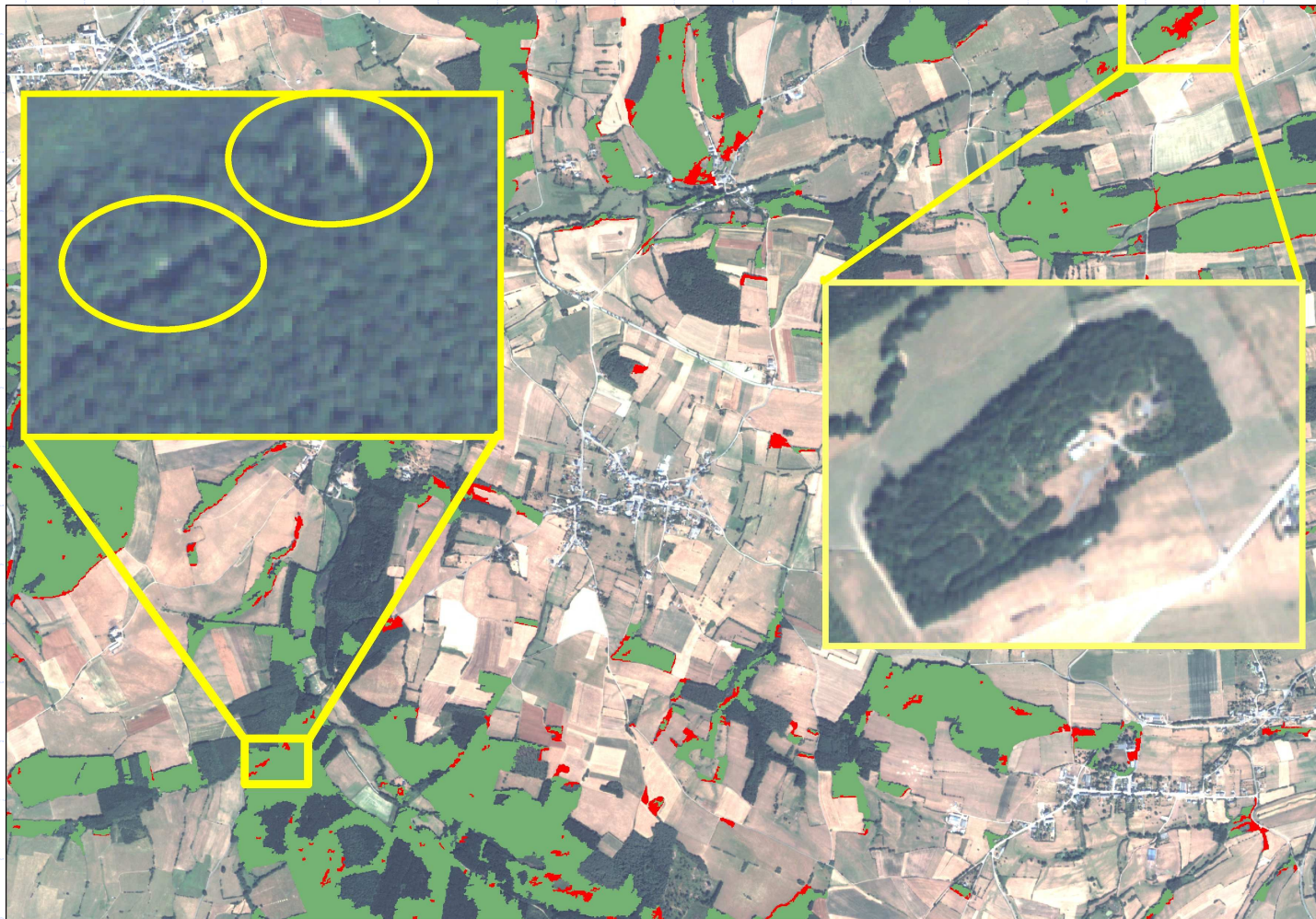


# Iterative trimming

- ◆ Assumes that outliers in the distribution are discrepancies
  1. Evaluate distribution parameters
    1. Bi-modal distribution (EM algorithm)
    2. Multinomial Gaussian
  2. Log-likelihood test for the best distribution
  3. Run until no more outliers
  
- 4. Calculate likelihood with final parameters



# Application example : forest change



# Conclusion and perspectives

- ◆ Good complementarity between the 2 parts
- ◆ Method detects thematic and planimetric discrepancies, but...
  1. Overdetection
    - Need to classify discrepancies (hope to see you in 2009)
  2. Not appropriate for linear objects
    - ◆ Use other methods (snakes, filters...)
  3. Validation is a real issue
    - ◆ Change, artefacts, fuzzy boundaries, semantic...

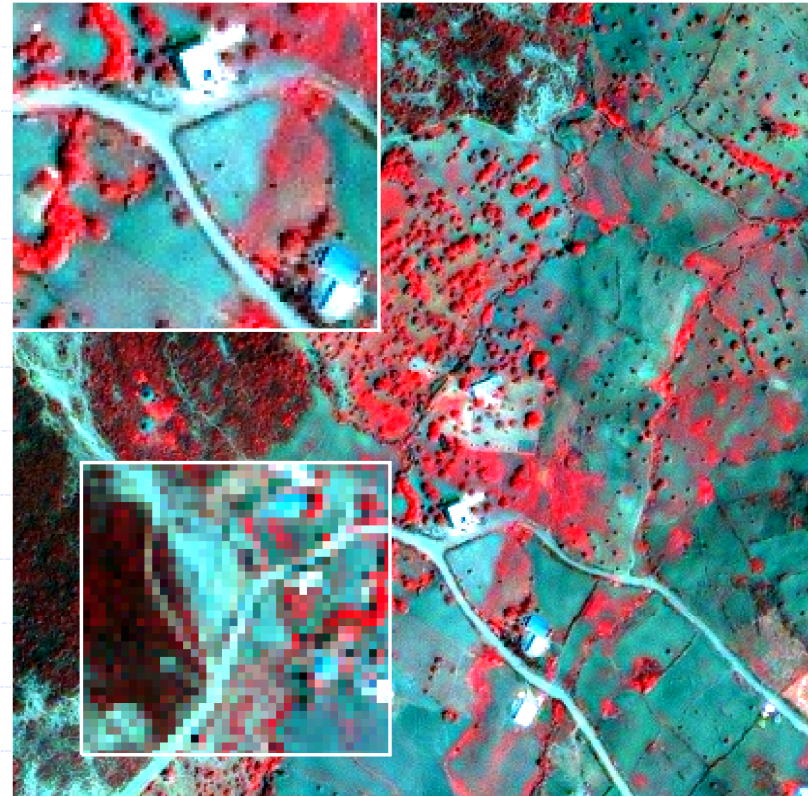


# Pansharpening tool for OTB

- ◆ Bayesian data fusion
  - Fasbender, Radoux and Bogaert
- ◆ Works with any optical image
  - Particularly good with VHR
- ◆ Adaptable
  - Tuning between « color » and « details »
    - ◆ Optimized for the application
    - ◆ Optimized for the study area



# Urban and rural examples





Thank you for your attention

