ULB Change detection for update of vector database through multi-level region-based classification of VHR data (ChaDe)

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Outline

- Introduction
- Objective
- Databases
- General method
- Applications and results
- Conclusion



Introduction

The local geospatial databases need to be updated

Interpretation of areal photographs

 \rightarrow Expensive and time-consuming task

- VHR satellite data (Pléiades HR and COSMO-Skymed data)
 - \rightarrow Advantages of the satellite images
 - Digital format
 - Large spatial coverage
 - Multispectral mode
 - •
 - \rightarrow Radar component
 - \rightarrow Very high resolution

Objective

- Study the potential of the Pléiades-HR data to detect change for update of vector databases through region-based classification
- Research network



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Royal Military Academy, Signal and Image Centre



University of Liège, Space Centre of Liège

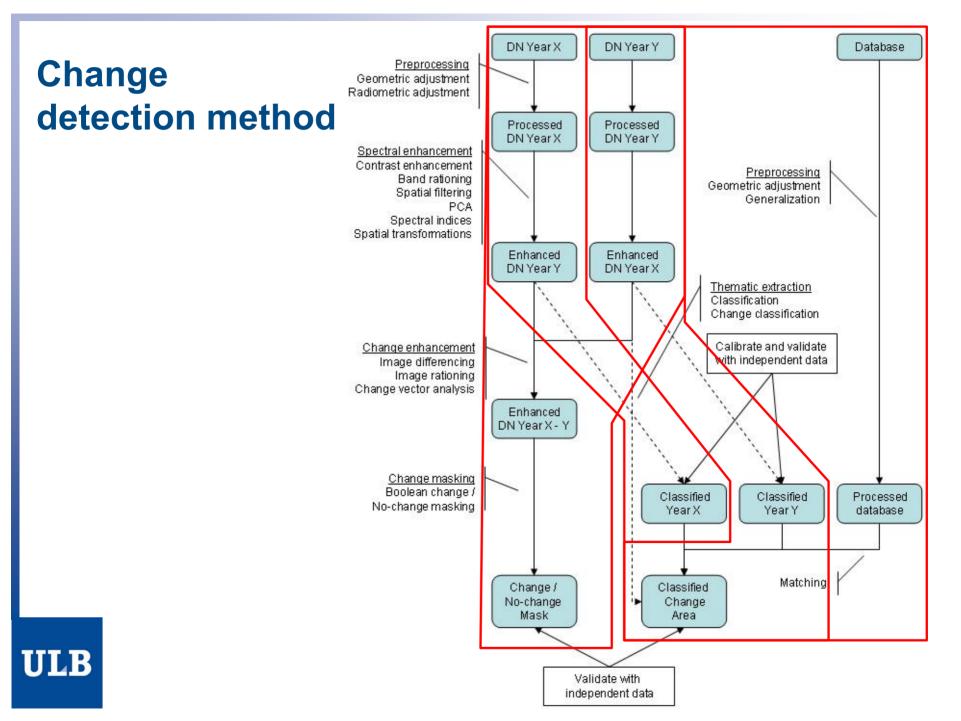


Databases

- National Geographical Institute
 1/10 000 topographic map (TOP10v-GIS)
 Ambitious database updating policy
 - Road network each year
 - Buildings each three year
 - Complete database each six years
- Agriculture Directorate-General (Walloon Region) Land Parcel Identification System (LPIS) Error database detection
 - Inclusions

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- Wrong delineation
- National Geographical Institute France
 - Topo-Pays: topographical map



Change detection method choice

Image-Database change detection method

 \rightarrow Matching and integration of raster and vector data

• Through a region-based classification

→ Overcome the poor spectral resolution and the high variability

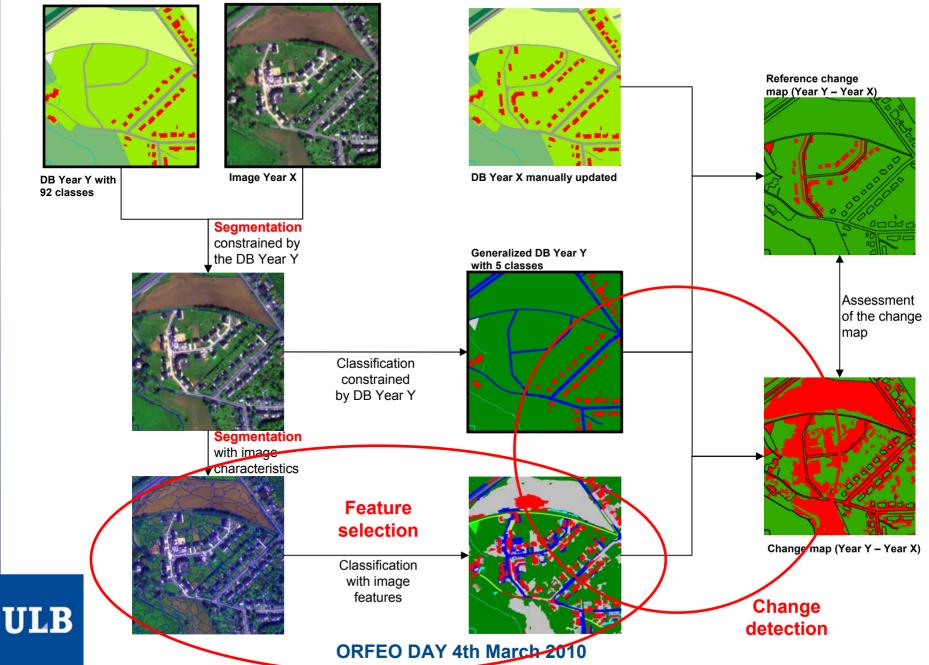


Study Area 1





Area 1



Features selection

- Bhatacharrya distance based on training sites
 - → <u>Vegetation</u>:
 - NDVI threshold
 - \rightarrow Shadows:
 - Panchromatic threshold
 - → Baren surfaces, Roads, Building, Water :
 - Panchromatic and Red bands
 - Contrast of Green and Red bands, Second Angular moment of Panchromatic band,
 - Length/Width



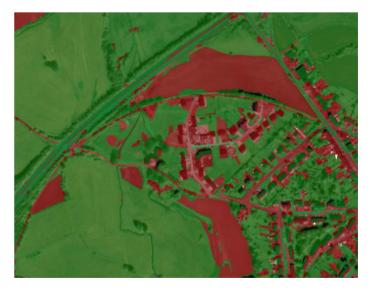
Area 1

Results

- Classification with the selected features
 - \rightarrow Change detection accuracy = 72%
 - → Transition detection accuracy = 70%

Classification detects 7.1 as much change than the reference and detects 90.5% of the true changes







Results

- Classification with features + rules about the gardens, crops and pastures
 - \rightarrow Change detection accuracy = 79%
 - → Transition detection accuracy = 78%

Classification detects 5.4 as much change than the reference and detects 90.7% of the true changes





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Results

- Classification with features + rules + class-related features for Building and Road
 - \rightarrow Change detection accuracy = 86%
 - → Transition detection accuracy = 84%

Classification detects 3.9 as much change than the reference and detects 88.4% of the true changes



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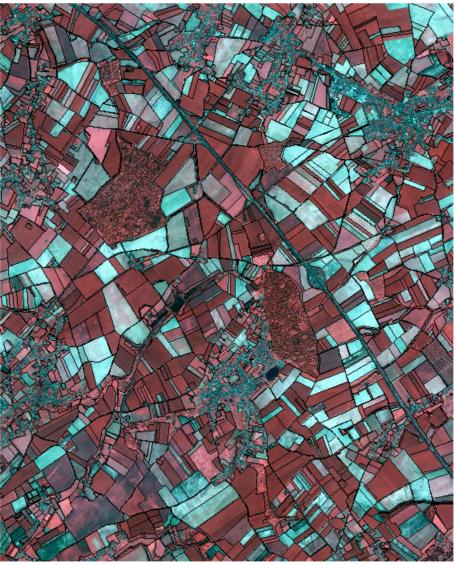
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Conclusions

- Very good results with all the transition classes
- Other rules in the classification
- Features selection optimization



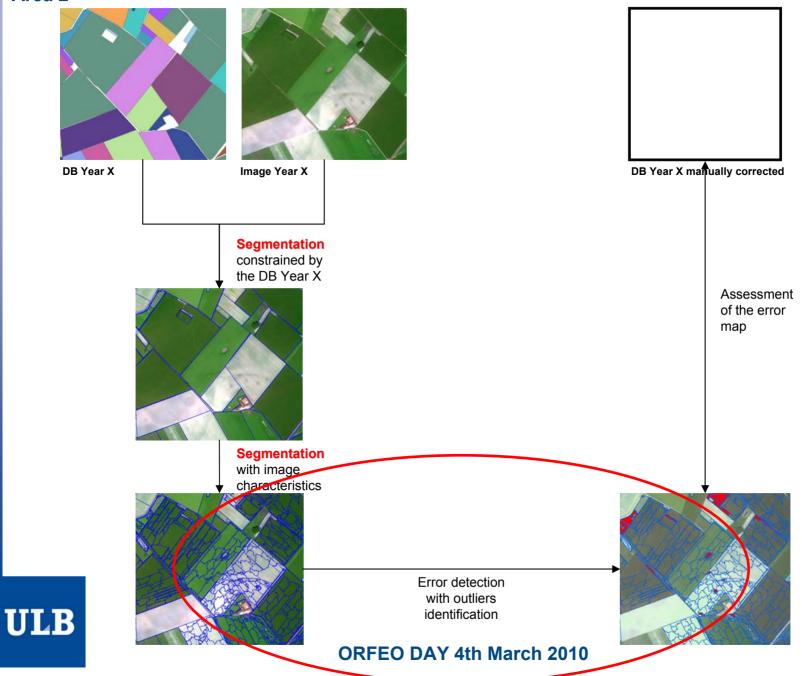
Study area 2





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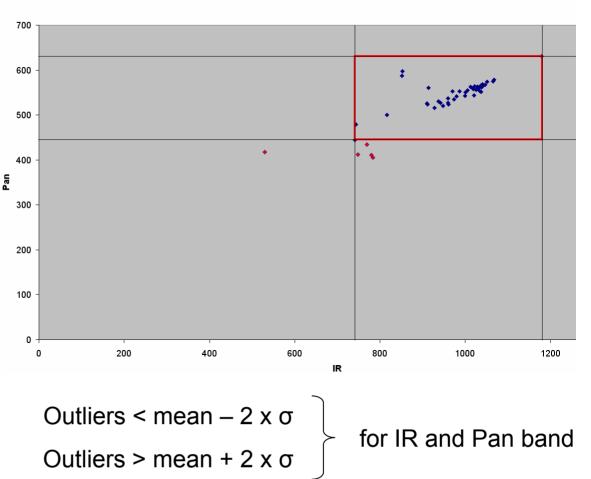
Area 2



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Outliers identification

Identification System

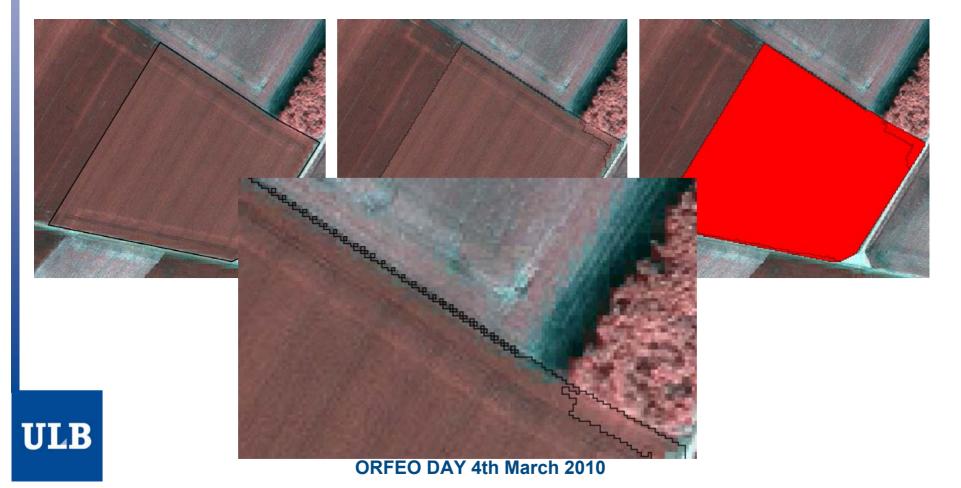


Outliers

Problems

Area 2

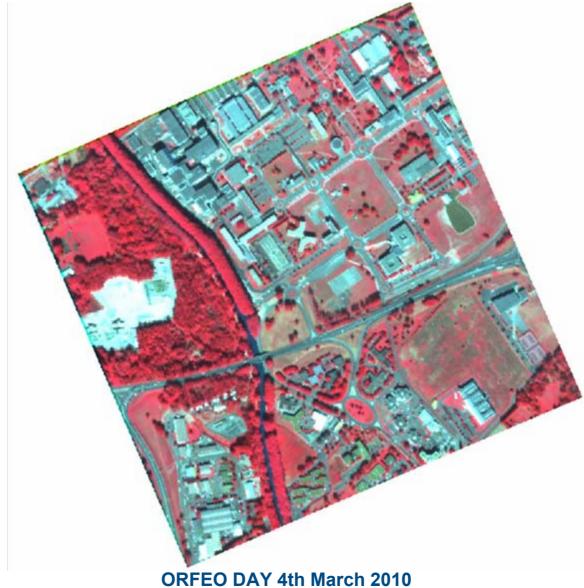
• Little segments become more important to identify outliers (mean and σ)



Conclusions

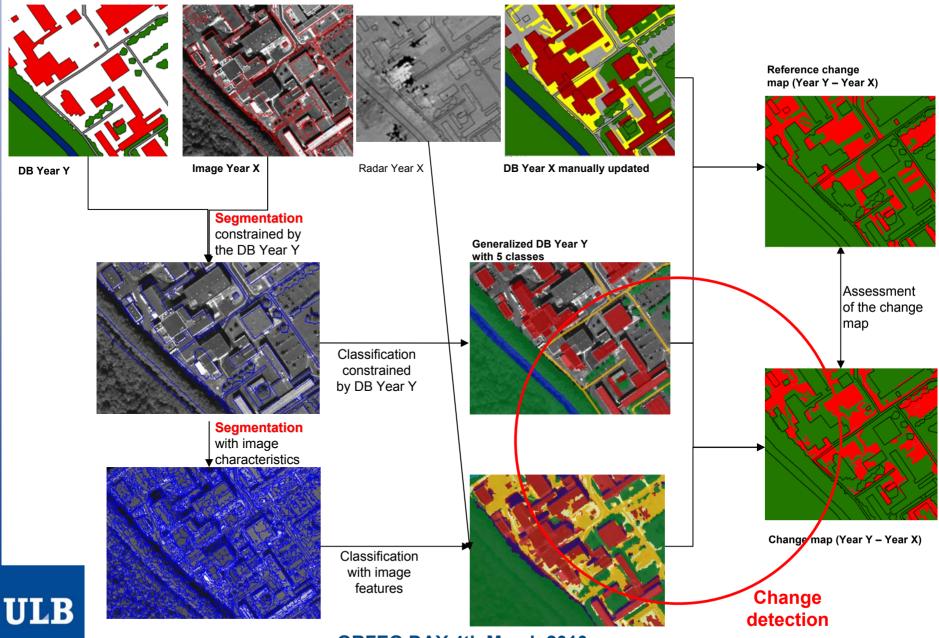
- Simple, good and unsupervised method
- Use of Minimum Mapping Unit (Regulation tolerance)
- Other outliers identification methods
- Other features to identify outliers
- Other study sites
- Identify wrong crops with the same method

Study Area 3



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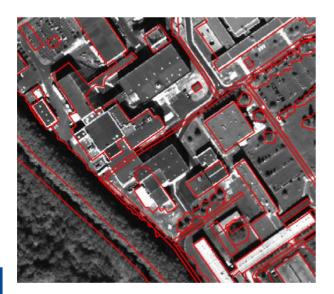
Area 3

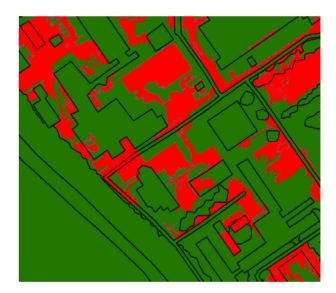


Results

• Kappa = 0.52

Classification detects 1.2 as much change than the reference and detects 65.7% of the true changes







Conclusions

- The method needs to be adapted with each database
- Utility of radar data

But

Need of a better resolution



General conclusions

Each method need optimization

Use of other segmentation method



Thank you for you attention

