

# SWIR and drones for early detection of oil spills in ports

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## Problem & Market





50 oil spills in 2019

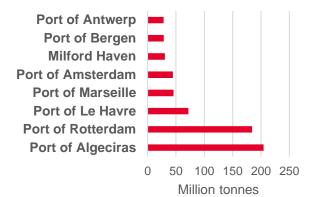


EUR 1.0 - 1.2 million (yearly)



Reimburse 40%

### Largest European oil traffic ports





638 million tonnes yearly

### **Operational System in Port**

Initial recognition of oil spill (detection, extent and oil type)

- < 2 minutes after arrival
- edge processing on drone platform
- real-time information streaming to emergency operations centre

Drone stays above oil spill (hoovering) - live oil spill severity measurement

**Post-processing** for more detailed information

- data transmission to processing server
- < 1 hour after data upload
- improved AI model
- identify source of the spill

# **Operational System in Port**

#### **Challenges**

- Fast detection
- Port environment
  - Docks = relatively small busy areas
  - Not much current, wind or waves
- Type of oil
  - Refined oils: hydraulic oil, lubricating oil, diesel, marine fuel & waste oil
- Selection of most appropriate cameras + limitations + cost / benefit
  - UV
  - Broadband RGB
  - Multispectral VNIR
  - (Multispectral) SWIR
  - LWIR

### SWIPE

**Period**: 01/07/2022 - 31/12/2023

The **objectives** of the project are:

(1) to develop an offline prototype workflow to detect & delineate oil spills during daytime from an airborne drone platform

(2) to demonstrate the technology in the port of Antwerp

The **result** will be a prototype workflow to detect oil spills at TRL 5-6, accompanied by a protocol for the camera settings and flight protocol.

#### The **innovation** in the project is:

(1) linked to the challenging application of the technology in a complex and harsh port environment

(2) the combined use of different camera systems

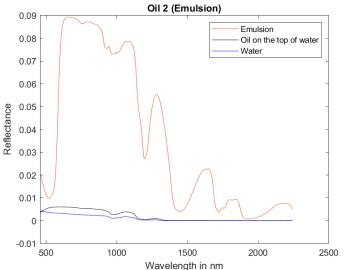


### Previous work: RGB + LWIR



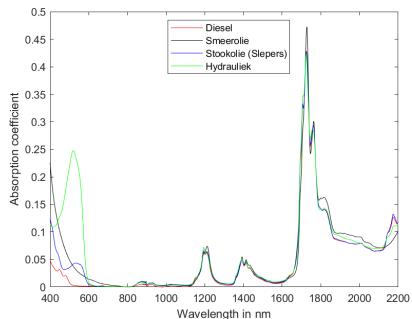


# SWIPE: Laboratory Measurements

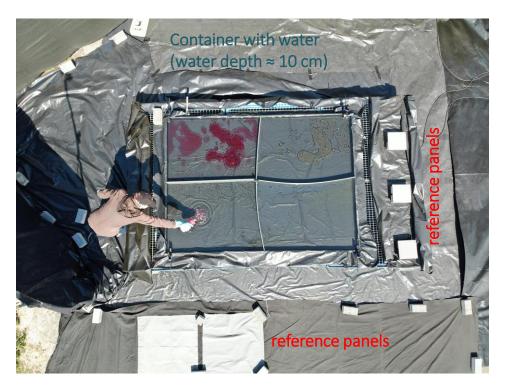


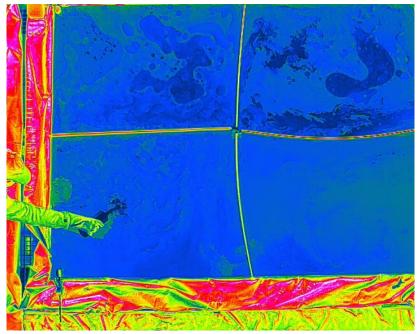
Visible range seems most promising Added value multispectral VNIR compared to broadband RGB Potential of UV range

#### SWIR is not useful for detection of pure oils except for oil emulsions



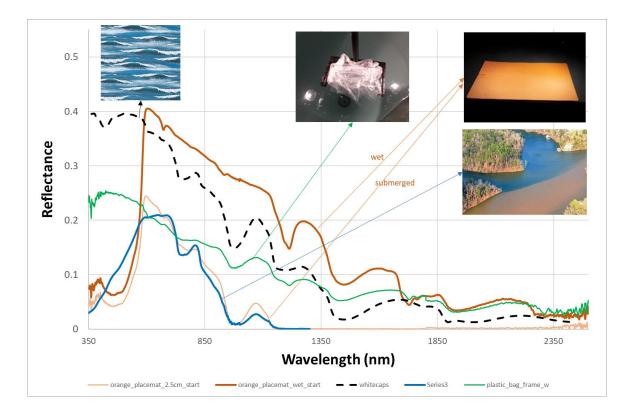
### SWIPE: Test Set-up (outdoors)





Data acquired: RGB / multispectral VNIR / multispectral SWIR / 3 x LWIR / 2 x irradiance

### **SWIPE: False Positives**



### SWIPE: Data Acquisition

- DroneMatrix
  - Network of drones capable of performing automated flights in the port
  - Drone-system 1: RGB + LWIR
  - Drone-system 2: multispectral VNIR
- Brabo Cleaning Company
  - System attached to monkey bridge of multicat
  - Multispectral VNIR + UV (+ LWIR)
  - Vessel dedicated to oil spill clean-up in port of Antwerp
- Historical dataset: small drone with RGB + LWIR

